



Prisma User Experiment Short Facts & Description Document

The Swedish Space Corporation (SSC) has developed the Prisma system, Prototype Research Instruments and Space Mission technology Advancement, to demonstrate critical technologies for enabling various types of proximity operations: rendezvous, sustained formation flying, collision avoidance, and more. SSC is now actively seeking User Experiments with Prisma that involve both short term, commercial-based ventures, as well as longer-term commitments and cooperation based on a joint and mutual interest. This document provides a structured set of questions aimed at helping a potential customer to define their Prisma User Experiment.

To obtain important information on the background of Prisma, the spacecraft capabilities and the scope of the User Experiment process, please read the whitepaper – "Stretching the Prisma Mission – an Invitation". The whitepaper is intended to give potential customers the initial information and guidelines necessary to determine whether the Prisma testbed is a good candidate for accomplishing their experiment objectives. It is available at: www.psatellite.com/prisma.php

Please return completed the completed form to the appropriate point of contact, listed below.

CONTACT INFORMATION

For non-US organisations:

Commercial Point of Contact

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1 – Which Units are Needed?		⊠Mango	⊠Tango
2 – Will the Experiment Use Delta-V?		□Yes	⊠No
If "Yes", how much Delta-V is Between and m/s	required?		
3 – Primary Sensor Systems			
⊠VBS Long Range ⊠VE ⊠Star Cameras ⊠Ra	PS Relative BS Short Range Ite Sensors Itreach & PR Telesc	cope / Camer	
4 - Experiment Timeline			
Duration of total experiment: Percentage of time performing Is there a requirement on the	orbital maneuvers	: <u>0</u> %.	s ⊠No
5 - Orbital Maneuvers			
Shortest Inter-Spacecraft Dista Longest Inter-Spacecraft Dista Maximum Relative Velocity:	ance: N/A n	neters neters neters / seco	nd
Maneuver Types (check all tha	at apply): Passive relative Sustained force Coarse relative Fine relative or	ed-motion orbit contro	•
6 - GNC Software			
Augmented: Prisr	ptions for the GNC only na GNC + Custom Com GNC only	BNC	·
Software-in-the-loop: Run ☐onboard or ☐on ☐ Run in the control lo ☐ Run in parallel with F ☐ Run offline and perfo	op in real-time. Prisma GNC.	on the grou	ınd





Custom GNC Components:	
Attitude/Rate Estimation	☐ Relative Orbit Navigation
Attitude/Rate Shaping	Relative Orbit Guidance
Attitude/Rate Control	Relative Orbit Control
_	Orbit Determination

7 - Success Criteria

Provide a brief definition of success at the end of the Experiment. Typically 2 to 5 sentences. What key results would you need in order to state that the Experiment has been successful or not?

The experiment will validate image processing algorithms that are used as inputs to an orbit and attitude estimator. The results will be deemed successful if the relative state estimates match the GPS states and attitude states measured by PRISMA.

8 - Narrative Description

Please describe in 1-3 pages the expected sequence of events and activities for the Experiment. Provide illustrations and diagrams in a separate attachment if necessary.

During normal operations video will be produced from the VBS. Each frame will be time-tagged. GPS and the attitude quaternion for the vehicles will also be collected.